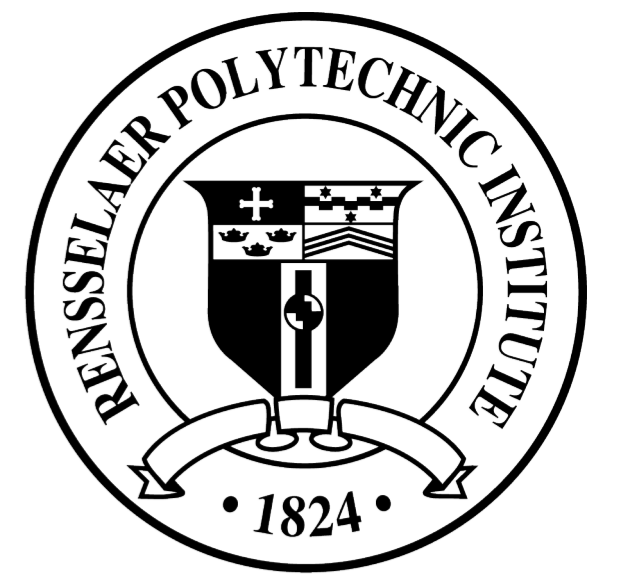
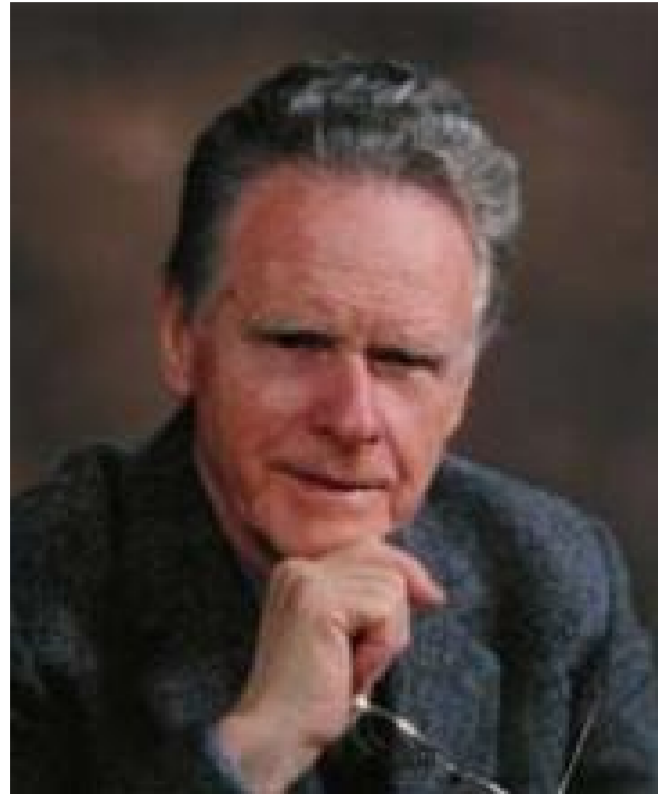


From Dempster to Lyapunov: A Dynamical Systems Approach to EM Algorithm Convergence

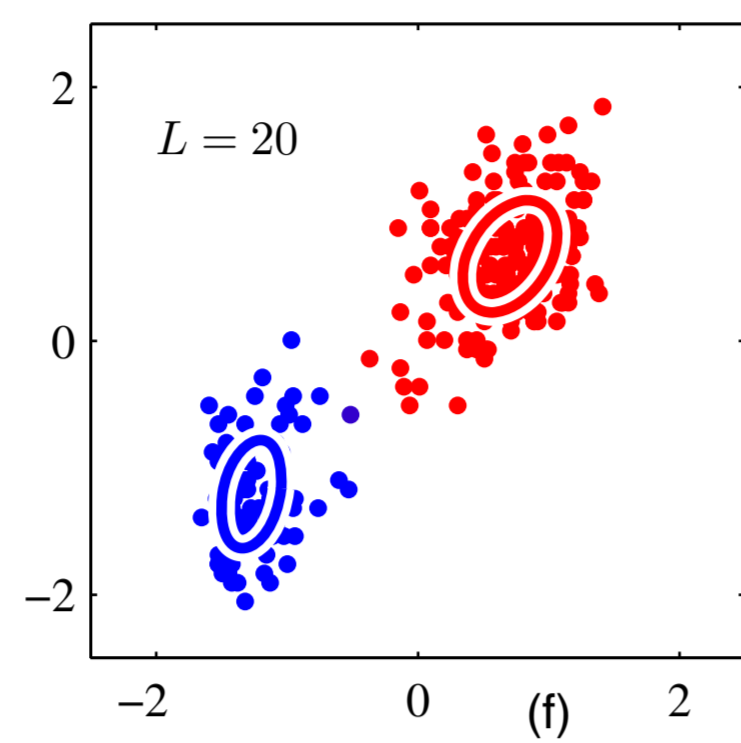


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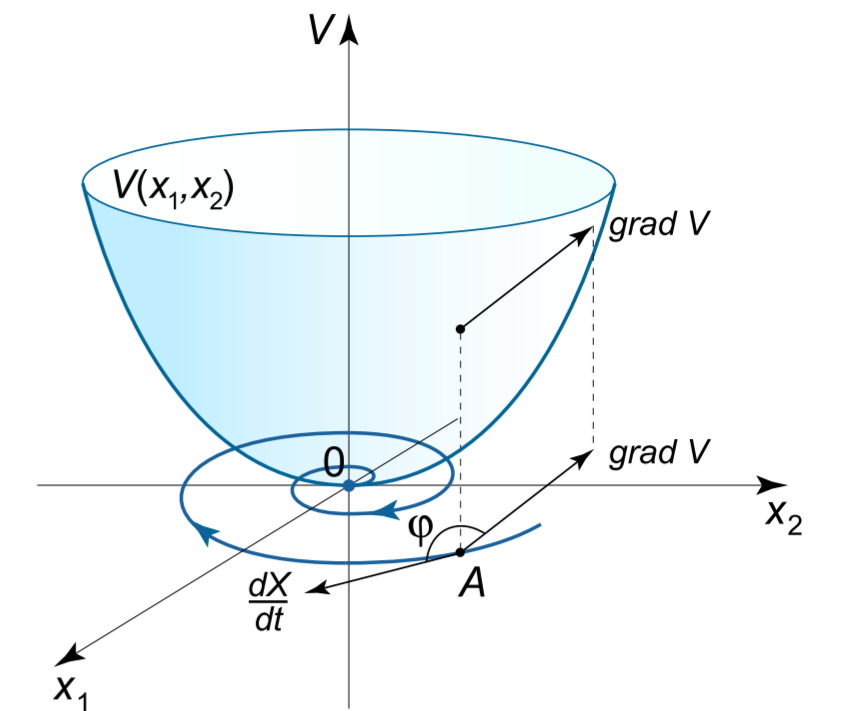
Arthur P. Dempster (1929 –)



EM Classification Example



Aleksandr Lyapunov (1857 – 1918)



Lyapunov Function Example

Framework – Parameter Estimation

- **Incomplete data:** $y \in \mathbb{R}^m$
- **Complete data:** $z = (x, y)$, $x \in \mathcal{X}$ is latent
- **Unknown parameter:** $\theta \in \Theta$
- **Statistical model:** $\{p_\theta(x, y) : \theta \in \Theta, x \in \mathcal{X}\}$
- $\hat{\theta}_{\text{ML}} \stackrel{\text{def}}{=} \operatorname{argmax}_{\theta \in \Theta} \mathcal{L}(\theta)$, where $\mathcal{L}(\theta) = p_\theta(y) = \int_{\mathcal{X}} p_\theta(x, y) dx$
- How to compute $\hat{\theta}_{\text{ML}}$?

Expectation-Maximization (EM) Algorithm

- $Q(\theta, \theta') \stackrel{\text{def}}{=} \mathbb{E}_{p_{\theta'}(x|y)}[\log p_\theta(x, y)] = \int_{\mathcal{X}} \frac{p_{\theta'}(x, y)}{p_{\theta'}(y)} \log p_\theta(x, y) dx$.
- 1: **initialize** $\theta_0 \in \Theta$
- 2: **for** $k = 1, 2, \dots$ **do**
- 3: **E-step:** Compute $Q(\theta, \theta_k)$
- 4: **M-step:** Determine $\theta_{k+1} = \operatorname{argmax}_{\theta \in \Theta} Q(\theta, \theta_k)$
- 5: **end for**
- 6: **return** θ_∞
- **Assumptions:**
 - $p_\theta(y) > 0$ for every $\theta \in \Theta$.
 - $\mathcal{X} = \{x \in \mathbb{R}^n : p_\theta(x, y) > 0\}$ does not depend on $\theta \in \Theta$.
 - for each $\theta' \in \Theta$, the function $Q(\cdot, \theta')$ as a unique global maximizer.
 - $\mathcal{L}(\theta)$ is twice continuously differentiable.
 - $\theta \mapsto p(\cdot|y)$ is injective.

Dynamical Systems Overview

- State-space model: $\theta[k+1] = F(\theta[k])$ with $\theta[0] = \theta_0$.
- θ^* is an *equilibrium* if $\theta_0 = \theta^* \implies \theta[k] = \theta^*$ for every k .
- θ^* is a *stable* equilibrium if $\forall \epsilon > 0, \exists \delta > 0$ such that $\|\theta_0 - \theta^*\| \leq \delta \implies \|\theta[k] - \theta^*\| \leq \epsilon$ for every k .
- θ^* is an *asymptotically stable* equilibrium if it is stable and $\exists \delta > 0$ such that $\|\theta_0 - \theta^*\| \leq \delta \implies \lim_{k \rightarrow \infty} \theta[k] = \theta^*$.
- θ^* is an *exponentially stable* equilibrium if it is stable and $\exists \delta, c, \gamma > 0$ such that $\|\theta_0 - \theta^*\| \leq \delta \implies \|\theta[k] - \theta^*\| \leq c \cdot e^{-\gamma k} \|\theta_0 - \theta^*\|$ for every k .

A Dynamical Systems Interpretation of EM

- $F(\theta') = F^{\text{EM}}(\theta') = \operatorname{argmax}_{\theta \in \Theta} Q(\theta, \theta') \implies \theta[k] = \theta_k$.
- θ^* is an equilibrium for $F = F^{\text{EM}} \iff \theta^*$ is a fixed point of EM.
- θ^* is asymptotically stable \implies EM is locally convergent to θ^* .

Lyapunov Theorem

Let θ^* be an equilibrium. If there exists a continuous function $\mathcal{V} : \Theta \rightarrow \mathbb{R}$ (*Lyapunov function*) such that

- \mathcal{V} is positive definite (w.r.t. θ^*), i.e. $\mathcal{V}(\theta^*) = 0$ and $\mathcal{V}(\theta) > 0$ for $\theta \neq \theta^*$;
 - $-\Delta \mathcal{V}$ is positive definite, where $\Delta \mathcal{V}(\theta) \stackrel{\text{def}}{=} \mathcal{V}(F(\theta)) - \mathcal{V}(\theta)$,
- then θ^* is asymptotically stable. Furthermore, if $\mathcal{V}(\theta) \leq a \|\theta - \theta^*\|^2$ and $-\Delta \mathcal{V}(\theta) \geq b \|\theta - \theta^*\|^2$, then θ^* is exponentially stable, with $c = d/a$, $d = \lim_{\delta \rightarrow 0} \max_{\|\theta - \theta_0\| \geq \frac{1}{2} \|\theta - \theta^*\|} \frac{\mathcal{V}(\theta)}{\|\theta - \theta^*\|}$, and $\gamma = \log a - \log(a - b)$.

Main Results

- **Theorem 1:** If $\nabla^2 \mathcal{L}(\hat{\theta}_{\text{ML}}) \prec 0$ then $\hat{\theta}_{\text{ML}}$ is asymptotically stable, and thus EM is locally convergent to $\hat{\theta}_{\text{ML}}$.
- **Proof:**
 - $Q(\theta, \theta') = \log \mathcal{L}(\theta) - \mathcal{D}_{\text{KL}}[p_{\theta'}(\cdot|y) \| p_\theta(\cdot|y)] - \mathcal{H}[p_{\theta'}(\cdot|y)]$
 - $F^{\text{EM}}(\hat{\theta}_{\text{ML}}) = \operatorname{argmax}_{\theta \in \Theta} \{\log \mathcal{L}(\theta) - \mathcal{D}_{\text{KL}}[p_{\hat{\theta}_{\text{ML}}}(\cdot|y) \| p_\theta(\cdot|y)]\}$
 - $(\log \mathcal{L}(\theta), \mathcal{D}_{\text{KL}}[p_{\hat{\theta}_{\text{ML}}}(\cdot|y) \| p_\theta(\cdot|y)])$ are maximized at $\theta = \hat{\theta}_{\text{ML}} \implies F^{\text{EM}}(\hat{\theta}_{\text{ML}}) = \hat{\theta}_{\text{ML}}$.
 - $\mathcal{V}(\theta) = \mathcal{L}(\hat{\theta}_{\text{ML}}) - \mathcal{L}(\theta)$ is positive definite w.r.t. $\hat{\theta}_{\text{ML}}$.
 - $\log \mathcal{L}(F^{\text{EM}}(\theta)) - \underbrace{\mathcal{D}_{\text{KL}}[p_\theta(\cdot|y) \| p_{F^{\text{EM}}(\theta)}(\cdot|y)]}_{>0 (\theta \neq \hat{\theta}_{\text{ML}})} \geq \log \mathcal{L}(\theta) - \underbrace{\mathcal{D}_{\text{KL}}[p_\theta(\cdot|y) \| p_\theta(\cdot|y)]}_{=0} \implies -\Delta \mathcal{V}(\theta) = \mathcal{L}(F^{\text{EM}}(\theta)) - \mathcal{L}(\theta)$ is also positive definite w.r.t. $\hat{\theta}_{\text{ML}}$.
- **Theorem 2:** If θ^* is a limit point of EM such that $\nabla^2 \mathcal{L}(\theta^*) \prec 0$, then it is asymptotically stable and thus EM is locally convergent to θ^* .
- **Proof:**
 - $(F^{\text{EM}}$ is continuous and θ^* is a limit point) $\implies F(\theta^*) = \theta^*$.
 - Repeat same argument for $\mathcal{V}(\theta) = \mathcal{L}(\theta^*) - \mathcal{L}(\theta)$ w.r.t. θ^* in a small enough open ball around θ^* .
- **Theorem 3:** In the same conditions of Theorem 2, and assuming $\mathcal{L}(F^{\text{EM}}(\theta)) - \mathcal{L}(\theta) \geq b \|\theta - \theta^*\|^2$ for some $b > 0$, then θ^* is exponentially stable and thus the linear convergence rate of EM can be explicitly bounded in terms of $\mathcal{L}(\theta)$.